

# Image Processing Using Scilab

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December 2, 2010

# Introduction to Digital Images

- Images can be Grayscale or Color (RGB)
- Specified as a matrix of size  $M \times N \times 3$  ( $M \times N$  for grayscale)

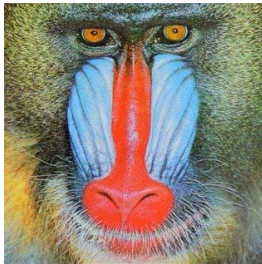
# Image Processing in Scilab

- Toolboxes - SIP (Scilab Image Processing) , SIVP (Scilab Image & Video Processing)
- We focus on SIVP Toolbox
- Installation in Ubuntu Linux - SIVP through atoms (5.3beta onwards), SIP through CVS (Both tested on Scilab 5.2.2)
- Installation in Windows - SIVP through atoms (5.3beta onwards), SIP (installed, not working yet)

# Grayscale and Color Images



(a) Gray Scale Image



(b) Color Image

# Image Read/Write/Show

1. Read Image - `lena = imread('lenagray.jpg')`
2. Show Image - `figure; imshow(lena)`
3. Write Image - `imwrite(lena,'lena.png')`

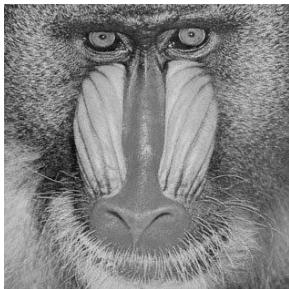
# Image Datatype Conversions

- im2int8
- im2int16
- im2int32
- im2uint8
- im2uint16
- im2double

# Image Conversions

- > *babbon* = *imread('bab.png')*;
- RGB to Gray scale - *rgb2gray*
  - > *babgray* = *rgb2gray(babbon)*;
- RGB to Binary - *im2bw*
  - > *lenabw* = *im2bw(lena, 0.5)*;
  - > *imwrite(lenabw, 'lenabw.png')*;
- RGB to HSV format - *rgb2hsv*
- HSV to RGB format - *hsv2rgb*
- RGB to YCbCr - *rgb2ycbcr*
- YCbCr to RGB - *ycbcr2rgb*

# Image Conversions - Results



(a) `rgb2gray(babbon)`;



(b) `im2bw(lena, 0.5)`;



# Basic Operations

- Crop -  
-- > *lenacrop = imcrop(lena, [200, 200, 200, 200]);*
- Complement -  
-- > *lenacomp = imcomplement(lena);*
- Resize -  
-- > *lenaresize = imresize(lena, 2, 'bicubic');*
  - The last term can be 'nearest', 'bilinear', 'bicubic' or 'area'

# Basic Operations - Complement



(a) Original



(b) Complement

# Basic Operations - Crop



(a) Original



(b) Cropped

# Basic Operations - Resize



(a) Original



(b) Resize by 2

# Add Noise

```
-- > lenaNgaussian = imnoise(lena,'gaussian');
```

The noise can be one of these:

1. salt & Pepper - white/black noise (default probability  $d=0.05$ )
2. speckle - multiplicative noise (uniform with mean 0 and variance  $v=0.04$ )
3. gaussian - additive noise (with mean 0 and variance  $v=0.01$ )

# Add Noise - Results



(a) Original



(b) Salt & Pepper



(c) Speckle



(d) Gaussian

# LTI Filter Kernels

Derivatives (High-Pass filter) using `fspecial`

- `sobel`  $\rightarrow$  `fspecial('sobel')`

$$\begin{pmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{pmatrix}$$

- `prewitt`  $\rightarrow$  `fspecial('prewitt')`

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ -1 & -1 & -1 \end{pmatrix}$$

- `laplacian`  $\rightarrow$  `fspecial('laplacian')`

$$\begin{pmatrix} 0.1666667 & 0.6666667 & 0.1666667 \\ 0.6666667 & -3.3333333 & 0.6666667 \\ 0.1666667 & 0.6666667 & 0.1666667 \end{pmatrix}$$

# LTI Filter Kernels Contd.

Blur (Low-Pass filter) using `fspecial`

- gaussian --  $\rightarrow$  `fspecial('gaussian')`

$$\begin{pmatrix} 0.0113437 & 0.0838195 & 0.0113437 \\ 0.0838195 & 0.6193470 & 0.0838195 \\ 0.0113437 & 0.0838195 & 0.0113437 \end{pmatrix}$$

- log --  $\rightarrow$  `fspecial('log')`

$$\begin{pmatrix} 0.0447924 & 0.0468064 & 0.0564068 & 0.0468064 & 0.0447924 \\ 0.0468064 & 0.3167464 & 0.7146325 & 0.3167464 & 0.0468064 \\ 0.0564068 & 0.7146325 & -4.904764 & 0.7146325 & 0.0564068 \\ 0.0468064 & 0.3167464 & 0.7146325 & 0.3167464 & 0.0468064 \\ 0.0447924 & 0.0468064 & 0.0564068 & 0.0468064 & 0.0447924 \end{pmatrix}$$

- average --  $\rightarrow$  `fspecial('average')`

$$\begin{pmatrix} 0.11111111 & 0.11111111 & 0.11111111 \\ 0.11111111 & 0.11111111 & 0.11111111 \\ 0.11111111 & 0.11111111 & 0.11111111 \end{pmatrix}$$



# Spatial Domain Processing

- FIR filters using `fspecial` `-- > h = fspecial('sobel');`
- Convolve 2D image with a 2D kernel `imfilter/filter2`  
`-- > lenaSobel = imfilter(lena, h);`
- Low-pass, High-pass filters realized

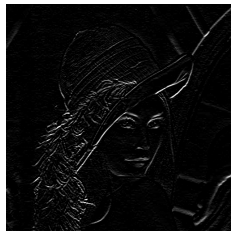
# Derivative Kernels - Results



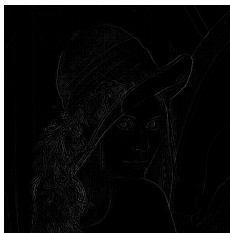
(a) Original



(b) Sobel



(c) Prewitt



(d) Laplacian

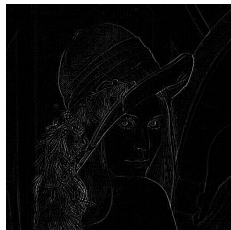
# Blurring Kernels - Results



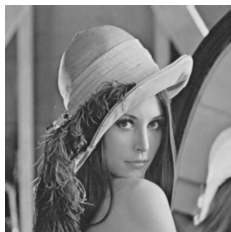
(a) Original



(b) Gaussian



(c) LoG



(d) Average

# Edge Detection

edge - High-pass filtering and thresholding

- Sobel --  $\>$  *lenaESobel* = *edge(lena,'sobel')*;
- Prewitt --  $\>$  *lenaEPrewitt* = *edge(lena,'prewitt')*;
- LoG --  $\>$  *lenaELog* = *edge(lena,'log')*;
- Canny --  $\>$  *lenaECanny* = *edge(lena,'canny')*;

# Edge Detection - Results



(a) Original



(b) Sobel



(c) Prewitt



(d) LoG



(e) Canny

# Miscellaneous

1. imhist - Histogram of the image --  $\> [counts, bins] = imhist(lena);$
2. imfinfo - Image Information --  $\> imfinfo('lena.jpg')$

# Gaussian Pyramid - Work Out

impyramid - Gaussian Smoothing and subsampling

```
-- > im0 = imread('lena.jpg');  
-- > im1 = impyramid(im0,'reduce');  
-- > im2 = impyramid(im1,'reduce');  
-- > im3 = impyramid(im2,'reduce');  
-- > imshow(im0);  
-- > imshow(im1);  
-- > imshow(im2);  
-- > imshow(im3);
```

# Image Compression

- Consider grayscale image as a matrix
- Take SVD  $I = U\Sigma V^T$
- Drop lowest singular values from diagonal matrix  $\Sigma$
- Reconstruct Image again



# Image Compression in Scilab

```
-- > A = imread('lena.jpg');  
-- > [u, s, v] = svd(double(A));  
-- > norm(u * s * v' - A) // just to check that A = u*s*v'  
-- > vdash = v';  
-- > svalues = diag(s); . // these are ordered increasing  
to decreasing  
-- > n = 100; // how many singular values of A we want  
to KEEP.  
-- > Alowerrank = u(:, [1 : n]) * diag(svalues(1 :  
n)) * vdash([1 : n], :);  
-- > imwrite(uint8(Alowerrank), 'lenaSVD100.png');
```

# Image Compression - Results



(a) Original



(b) Top 20



(c) Top 40



(d) Top 60



(e) Top 80



(f) Top 100

# Advanced Topics - To be Explored

- FFT
- Wavelets
- Radon Transform
- Hough Transform

# Recap

1. Read/Write/Show Image
2. Basic Operations
3. Noise and Blur
4. LTI Filtering
5. Image as a Matrix
6. Transform Domain Operations

# Thanks

Thank You  
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