Fractional Calculus and Fractional Differential Equations with SCILAB

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By

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Fractional Calculus and Fractional Differential Equations with SCILAB

- What is Fractional Calculus
- Historical Review
- Definitions
- Applications
 - Fractional-order modeling
 - Fractional-order control

- All of us are familiar with *normal* derivatives and integrals, like, $\frac{df}{dt}$, $\frac{d^2f}{dt^2}$, $\int_0^t f(u)du$.
- We have first-order, second-order derivatives, or first integral, double integral, of a function.
- Now we wish to have half-order, π th-order, or (3-6i)th-order derivative of a function.
- So, Fractional calculus ⇒ derivatives and integrals of arbitrary real, or complex order

So what? Answer these questions.....

- Does it make any sense? Or is just a mathematical fantasy? Define it.
- Tell me how to calculate the 1/2-order derivative of f(t) = t.
- This seems to be a recent stuff. How old is it?
- Does it have any physical interpretation/geometrical meaning?
- Why study it? How is it important in engineering? What's the deal?
- How much serious is the research community about it?
- What are its applications?
- So should we discard the integer-order derivatives?

- As old as normal, conventional, integer-order calculus.
- Born in **1695**!!
- In a letter correspondence, l'Hôpital asked Leibniz: "What if the order of the derivative is 1/2"?
- To which Leibniz replied in a prophetical way, "Thus it follows that will be equal to $x^2 \sqrt[2]{dx : x}$, an apparent paradox, from which one day useful consequences will be drawn."
- This letter of Leibniz was dated 30th September, 1695. So **30th September** is considered as the **birthday** of fractional calculus.

Contributors

- Leibniz (1695)
- Euler (1730)
- Lagrange (1772)
- Laplace (1812)
- Fourier (1822)
- Abel (1823)
- Liouville (1832)
- Riemann (1876)

- Fifteen Books.
- Two dedicated international journals.
- **First** international conference on "Fractional Calculus and its Applications" in June, 1974 in US.
- Special international conference conducted (first was in 2004) by the International Federation of Automatic Control (IFAC) every two years: **Fractional Differentiation and its Applications**.
- More than 5000 papers published on the single topic of modeling of complex systems by fractional differential equations.

Indians Working in Fractional Calculus

- Prof. H. M. Srivastava, University of Victoria, Canada
- 2 Prof. Loknath Debnath, The University of Texas-Pan American, US
- Prof. Lakshmikantham, Florida Institute of Technology, US
- O Prof. Gangal, University of Pune
- Prof. Saxena, Jai Narain Vyas University, Jodhpur
- **o** Prof. Mathai, McGill University, Canada
- Prof. Arun Kolwankar, Ramniranjan Jhunjhunwala college, Mumbai
- In Mr. Shantanu Das, Scientist, Bhabha Atomic Research Center, Mumbai
- Prof. Anindya Chatterjee, Indian Institute of Science, Bangalore
- Prof. S. Sen, IIT Kharagpur
- 🔱 Prof. Arijit Biswas, Jadavpur University, Kolkata
- 😰 Prof. (Mrs.) Varsha Gejji, University of Pune

- Rigorous mathematical theory has been developed.
- Integer-order calculus is the special case.
- Geometrical interpretation or physical meaning exists. But not as straight forward as for the integer-order derivatives.
- There are more that FIFTEEN definitions of fractional derivative operator.

Some Mathematics: Successive Differentiation

• *n*th-order derivative of t^n (*n* is integer)

$$\frac{d^n}{dt^n}t^n = n!$$

• *n*th-order derivative of t^m , m, n integers, m > n is

$$\frac{d^n}{dt^n}t^m = \frac{m!}{(m-n)!}t^{m-n}$$

• Use the Euler's Gamma function (Γ) property,

$$n! = \Gamma(n+1)$$

So we can re-write

$$\frac{d^n}{dt^n}t^m = \frac{\Gamma(m+1)}{\Gamma(m-n+1)}t^{m-n}$$

• Gamma function is defined for positive and negative reals (except for negative integers and zero). So we let *m* and *n* to be reals.

Some more Mathematics

• We define fractional derivative of order $\alpha \in \mathbf{R}$, $\alpha \geq 0$, of t^{μ} , $\mu \in \mathbf{R}$:

$$rac{d^lpha}{dt^lpha}t^\mu:=D^lpha_tt^\mu=rac{{\sf \Gamma}(\mu+1)}{{\sf \Gamma}(\mu-lpha+1)}t^{\mu-lpha}$$

• Here the condition $\mu > \alpha$ can be relaxed.

Let's Start!!

1

2

3

$$\frac{d^{0.5}}{dt^{0.5}}t^{0.5} = \Gamma(1+0.5) = \Gamma(1.5)$$

$$\frac{d^{0.5}}{dt^{0.5}}t = \frac{1}{\Gamma(1.5)}t^{0.5}$$

$$rac{d^{0.5}}{dt^{0.5}}(1) = rac{1}{\sqrt{\pi t}}
eq 0$$

Some more Mathematics: Successive Integration

• Let's take the first integral a function f(t)

$$J^1f(t):=\int_0^t f(u)du, \quad t>0,$$

• Let's integrate it once more.

$$J^2f(t):=\int_0^t\int_0^u f(v)dvdu,\quad t>0,$$

• Successive integration of f(t) for *n*-times (*n*, integer) is:

$$J^n f(t) := \int_0^t \int_0^u \dots \int_0^w f(v) dv dw \dots du, \quad t > 0,$$

• Cauchy provided a closed-form formula for *n* successive integrations:

$$J^n f(t) := rac{1}{(n-1)!} \int_0^t (t-u)^{(n-1)} f(u) du, \quad t > 0.$$

• Again, the same trick!! Replace factorial by Gamma function.

• The Riemann-Liouville (RL) fractional integral of order $0 \le \alpha \le 1$ is defined as

$$J^{\alpha}f(t):=rac{1}{\Gamma(\alpha)}\int_0^t(t-u)^{(\alpha-1)}f(u)du,\quad t>0,$$

We can define fractional derivative of order α by two ways:
 RL fractional derivative: Take fractional integral of order (1 - α) and then take a first derivative,

$$D_t^{\alpha}f(t) = rac{d}{dt}J^{1-lpha}f(t)$$

Caputo fractional derivative: Take first order derivative and then take a fractional integral of order (1 - α),

$$D_t^{\alpha}f(t) = J^{1-\alpha}rac{d}{dt}f(t)$$

Did you notice?

- Definition of fractional derivative involves an integration.
- Integration is a non-local operator (as it is defined on an interval).
- \Rightarrow Fractional derivative is a non-local operator.
- \Rightarrow Calculating time-fractional derivative of a function f(t) at some $t = t_1$ requires all the past history, i.e. all f(t) from t = 0 to $t = t_1$.
- $\bullet \Rightarrow$ Fractional derivatives can be used for modeling systems with memory.
- \Rightarrow Calculating space-fractional derivative of a function f(x) at $x = x_1$ requires all non-local f(x) values.
- → Fractional derivatives can be used for modeling distributed parameter systems.

Fractional Differential Equations (FDEs)

- Differential equations involving fractional derivatives.
- Example: Bagley-Torvik equation of oscillatory processes with fractional damping:

$$\frac{d^2}{dt^2}y(t) + aD_t^{1.5}y(t) + by(t) = f(t)$$

- Both ODEs and PDEs.
- Linear and non-linear.
- Existence and uniqueness of solutions established.
- Analytical solutions are difficult to evaluate.
- Dedicated, elegant numerical methods exist.

- In spite of its long history, fractional calculus was not considered eligible for any applications.
- This was due to its high complexity and lack of physical and geometric interpretation.
- Application of fractional calculus to real-world problems is only four decades old.
- Applications can be broadly categorized into:
 - **1** Modeling of Systems
 - **2** Fractional-order Control

Diffusion

- Normal, Fickian diffusion ⇒ flow of particles from high concentration to low concentration ⇒ Concentration is given by Gaussian distribution
- Asymptotical mean-squared displacement is a linear function of time,

 $\langle x^2(t) \rangle \sim t$

• Model is given by diffusion equation

$$rac{\partial \phi(x,t)}{\partial t} = D rac{\partial^2 \phi(x,t)}{\partial x^2}$$

Diffusion (continued)

- Some processes are an exception to this.
- Example: Photocopy machine and Laser printer. Movement of holes and electrons in the semiconductors inside them is not the normal, Gaussian diffusion.
- It is the Anomalous diffusion.
- Asymptotical mean-squared displacement is **not** a linear function of time,

$$\langle x^2(t) \rangle \sim t^{\alpha}, \quad \alpha \neq 1$$

- $\alpha < 1 \Rightarrow$ Sub-diffusion \Rightarrow Slow movement of particles.
- $\alpha > 1 \Rightarrow$ Super-diffusion \Rightarrow Fast movement of particles.
- Fractional diffusion equation model is

$$rac{\partial^lpha \phi(x,t)}{\partial t^lpha} = D_lpha rac{\partial^2 \phi(x,t)}{\partial x^2}$$

• Sub-diffusion:

- Transport of holes and electrons inside the amorphous semiconductors under the electric field.
- Ø Movement of contaminants in groundwater.
- Spread of pollutants from environmental accidents.
- Oliffusion of proteins across cell membranes.

• Super-diffusion:

- **1** Motion of large molecules and metal clusters across crystalline surfaces.
- Ilight of seabirds (Albatrosses).
- Movement of spider monkeys.
- Spread of pollutants in the sea.
- Movement of particles inside a rapidly rotating annular tank.

Applications of Fractional Calculus: A Panoramic View

- Viscoelastic materials.
- Polymeric materials.
- Acoustic wave propagation in inhomogeneous porous material.
- Fluid flow.
- Dynamical processes with self-similar structures.
- Dynamics of earthquakes.
- Optics.
- Geology.
- Bio-sciences.
- Medicine.

Applications of Fractional Calculus: A Panoramic View

- Electrical engineering: element Fractance.
- Economics.
- Probability and statistics.
- Astrophysics.
- Chemical engineering.
- Signal processing.
- Chaotic dynamics.
- Even fractional-order models of LOVE and EMOTIONS have been developed!!! And they are claimed to give better representation than the integer-order ODEs!!!

- **Confessions of a Fractional Calculus Researcher:**
- "As soon as I see integer-order derivatives in an equation, I replace them with the fractional ones. <u>Then</u> I start worrying about the motivation for the replacement."

Fractional-order Control

- Lots of derivatives and integrals in control theory!!
- If the model is fractional order, why not the controller?
- Example: Standard Proportional-Integral-Derivative (PID) controller.
- Replace the integral and derivative terms by fractional ones. So we get a *fractional* PID, i.e. $PI^{\alpha}D^{\beta}$ controller.
- So we do the fractional differentiation and integration of the error signal.
- Fractional PID and other fractional controllers have been found to provide a more efficient control of the fractional-order systems.
- A typical fractional-order transfer function looks like:

$$rac{Y(s)}{U(s)} = rac{b_1 s^{eta_1} + b_0}{a_2 s^{lpha_2} + a_1 s^{lpha_1} + a_0}$$

FO-controllers proposed in the literature

- Fractional PID (Podlubny)
- Fractional State-space controller (Oustaloup)
- Fractional-order controller for multivariable system (M Rachid)
- Fractional-order Quantitative Feedback Theory (QFT) controller (PSV Nataraj)
- Fractional-order Disturbance Observer (YQ Chen)
- Fractional-order control of non-linear systems (Delavari)
- Fractional-order QFT control of non-linear systems (PSV Nataraj)
- Fractional-order optimal control (OP Agrawal)

Some Issues about Fractional-order Control System

- We can tell its order.
- We can draw the root locus.
- We can check the stability.
- We can simulate it.
- We can implement it in the real-time.
- We can check its controllability and observability.
- We can draw its Bode, Nicols, Nyquist plots.
- We can design fractional lead-lag controller.

- The basis of fractional-order modeling and fractional-order controller is **Fractional Differential Equations (FDEs)**.
- No commercial software has a dedicated toolbox for FDEs.
- We are trying to develop an "FDE toolbox" in SCILAB.
- We are using numerical methods.
- We are presently working on linear, one-term and multi-term FDEs.

"We have not succeeded in answering all our problems. The answers we have found only serve to raise a whole set of new questions. In some ways we feel we are as confused as ever, but we believe we are confused on a higher level and about more important things."